

Tutorial – 13

Exam Text of 24/02/2005

Problem 1

The temperature of a biochemical reaction in a test tube varies from 30°C to 40°C and we want to measure the temperature variation with high precision once per second. A Platinum RTD (Resistive Temperature Detector) featuring $R_{T0}=100\Omega$ at the reference temperature of 20°C is exploited. A Wheatstone bridge readout configuration with 3 resistors and the RTD is exploited. The power dissipation on the sensor has to be kept below 1μW. The power supply of the bridge V_A is a pulsed periodical voltage with a duration $T_A=100\text{ms}$ and period $T_r=1\text{s}$. The signal is readout by means of a voltage preamplifier featuring a bandwidth limited by a single pole $f_p=100\text{kHz}$. The noise referred to the input of the preamp is given by the following contributions, expressed in terms of unilateral noise spectral densities: current white noise $\sqrt{S_I} = 1\text{pA}/\sqrt{\text{Hz}}$, voltage noise $\sqrt{S_V} = S_W + K/f$ with $\sqrt{S_W} = 10\text{nV}/\sqrt{\text{Hz}}$ and corner frequency $f_c=5\text{kHz}$.

First of all, sketch and describe the configuration of the setup. Then:

- Select a simple filtering stage that limits the 1/f noise contribution and considering only this filter and the preamp evaluate the noise affecting this measurement.
- Evaluate the precision that can be achieved with the setup of point a in terms of minimum temperature that can be measured.
- Select an additional filtering stage to improve the sensitivity of the system. Repeat the evaluations of point a) and b).

Problem 2

Consider the same setup of problem 1 with a sinusoidal voltage having maximum amplitude V_A and frequency $f_A=500\text{Hz}$ applied to the Wheatstone bridge.

- Select a simple filtering stage that limits the 1/f noise contribution. Considering only this filter and the preamp, evaluate the noise affecting this measurement and the minimum temperature that can be measured.
- Now add a resonant filter tuned at f_A and having quality factor $Q=5$. Repeat the evaluations of point a).
- In order to improve the precision of the measurement, how would you change the bias of the Wheatstone bridge and/or the filtering stage following the preamp? Paying attention to comply with the requirements of Problem 1, describe the new setup and repeat the evaluations of point a).

- A)** To filter the $1/f$ component we can use a high-pass CR filter, to avoid effects on the signal we choose $f_{HPF} = 0.1\text{ Hz}$, the total noise is equal to:

$$\sigma_v = \sqrt{(S_W + S_I R^2) \cdot \frac{\pi}{2} f_P + S_W \cdot f_c \cdot \ln\left(\frac{f_P}{f_{HPF}}\right)} \cong 4.75 \mu\text{V}$$

- B)** To find the minimum variation measurable we need to know the value of the power supply:

$$P_{\text{sensor}} = \left(\frac{V_A}{2}\right)^2 \cdot \frac{1}{R} \cdot \frac{T_A}{T_R} \rightarrow V_A = \sqrt{4P_{\text{sensor}} R \frac{T_R}{T_A}} \cong 63.2 \text{ mV}$$

The minimum variation of the temperature measurable by the system is:

$$\Delta T_{\min} = \sigma_v \cdot \frac{4}{V_A \alpha} \cong 75 \text{ mK}$$

- C)** We can further improve the measurement using a Gated integrator of duration $T_G = T_A = 100 \text{ ms}$ and a sync signal synchronous to the power supply, in this case, the noise is equal to:

$$\sigma_v = \sqrt{(S_W + S_I R^2) \cdot \frac{1}{2T_G} + S_W \cdot f_c \cdot \ln\left(\frac{f_{GI}}{f_{HPF}}\right)} \cong 1.4 \mu V$$

The minimum variation of the temperature measurable by the system is:

$$\Delta T_{min} = \sigma_v \cdot \frac{4}{V_A \alpha} \cong 22 \text{ mK}$$

SECOND PROBLEM

- A)** To filter the $\frac{1}{f}$ component we can use a high-pass CR filter, given the signal is modulated around $f_A = 500 \text{ Hz}$ we can use a $f_{HPF} = 50 \text{ Hz}$, the total noise is equal to:

$$\sigma_v = \sqrt{(S_W + S_I R^2) \cdot \frac{\pi}{2} f_P + S_W \cdot f_c \cdot \ln\left(\frac{f_P}{f_{HPF}}\right)} \cong 4.41 \mu V$$

To find the minimum variation measurable we need to know the value of the power supply:

$$P_{sensor} = \frac{1}{2} \left(\frac{V_A}{2}\right)^2 \cdot \frac{1}{R} \rightarrow V_A = \sqrt{8P_{sensor} R} \cong 28 \text{ mV}$$

The minimum variation of the temperature measurable by the system is:

$$\Delta T_{min} = \sigma_v \cdot \frac{4}{V_A \alpha} \cong 156 \text{ mK}$$

- B)** Using a resonant filter tuned around f_A we obtain a bandwidth of:

$$BW = \frac{\pi f_A}{2 Q} \cong 157 \text{ Hz}$$

The total noise is equal to:

$$\sigma_v = \sqrt{(S_W + S_I R^2) \cdot BW + S_W \cdot f_c \cdot \ln\left(\frac{f_P}{f_{HPF}}\right)} \cong 415 \text{ nV}$$

The minimum variation of the temperature measurable by the system is:

$$\Delta T_{min} = \sigma_v \cdot \frac{4}{V_A \alpha} \cong 15 \text{ mK}$$

- C)** To further improve the system, we can increase f_A beyond the noise corner frequency of the noise, for example, we can use $f_A = 10 \text{ KHz}$, then we can use a LIA with a low-pass filter (i.e. $f_{LPF} = 10 \text{ Hz}$) to extract the measurement.

The total noise is equal to:

$$\sigma_v = \sqrt{\left(S_W + S_I R^2 + S_W \cdot \frac{f_c}{f_A}\right) \cdot \frac{\pi}{2} f_{LPF}} \cong 69 \text{ nV}$$

The minimum variation of the temperature measurable by the system is:

$$\Delta T_{min} = \sigma_v \cdot \frac{4}{V_A \alpha} \cong 2.4 \text{ mK}$$